
UNIT-4

Sorting

Bringing Order to the World

Lecture Outline

- Iterative sorting algorithms (comparison based)
 - Selection Sort
 - Bubble Sort
 - Insertion Sort
 - Recursive sorting algorithms (comparison based)
 - Merge Sort
 - Quick Sort
- Note: we only consider sorting data in **ascending order**

Why Study Sorting?

- When an input is sorted, many problems become easy (e.g. **searching**, **min**, **max**, **k-th smallest**)
- Sorting has a variety of interesting algorithmic solutions that embody many ideas
 - Comparison vs non-comparison based
 - Iterative
 - Recursive
 - Divide-and-conquer
 - Best/worst/average-case bounds
 - Randomized algorithms

Applications of Sorting

- Uniqueness testing
- Deleting duplicates
- Prioritizing events
- Frequency counting
- Reconstructing the original order
- Set intersection/union
- Finding a target pair x, y such that $x+y = z$
- Efficient searching

Selection Sort

Selection Sort: Idea

- Given an array of n items
 1. Find the largest item x , in the range of $[0 \dots n-1]$
 2. Swap x with the $(n-1)^{\text{th}}$ item
 3. Reduce n by 1 and go to Step 1

Selection Sort: Illustration

29	10	14	37	13
----	----	----	----	----

37 is the largest, swap it with the last element, i.e. **13**.

Q: How to find the largest?

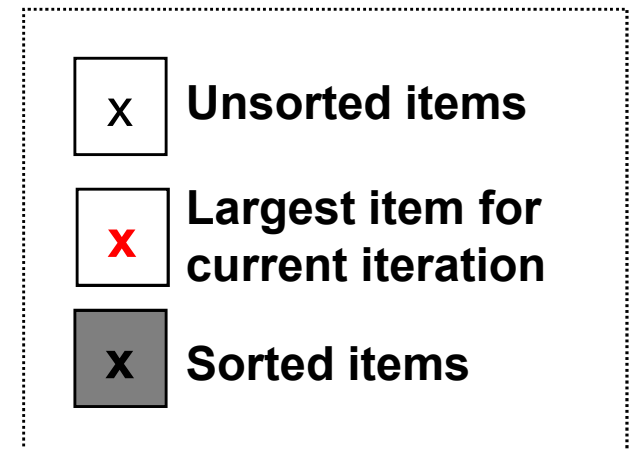
29	10	14	13	37
----	----	----	----	----

13	10	14	29	37
----	----	----	----	----

13	10	14	29	37
----	----	----	----	----

10	13	14	29	37
----	----	----	----	----

Sorted!



We can also find the smallest and put it the front instead

<http://visualgo.net/sorting?create=29,10,14,37,13&mode=Selection>

Selection Sort: Implementation

```
void selectionSort(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        int maxIdx = i;  
        for (int j = 0; j < i; j++)  
            if (a[j] >= a[maxIdx])  
                maxIdx = j;  
        // swap routine is in STL <algorithm>  
        swap(a[i], a[maxIdx]);  
    }  
}
```

Step 1:
Search for
maximum
element

Step 2:
Swap
maximum
element
with the last
item i

Selection Sort: Analysis

```
void selectionSort(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        int maxIdx = i;  
        for (int j = 0; j < i; j++)  
            if (a[j] >= a[maxIdx])  
                maxIdx = j;  
        // swap routine is in STL <algorithm>  
        swap(a[i], a[maxIdx]);  
    }  
}
```

Number of times
executed

■ $n-1$

■ $n-1$

■ $(n-1)+(n-2)+\dots+1$
= $n(n-1)/2$

■ $n-1$

Total

= $c_1(n-1) +$

$c_2 * n * (n-1)/2$

= $O(n^2)$

- c_1 and c_2 are cost of statements in outer and inner blocks

Bubble Sort

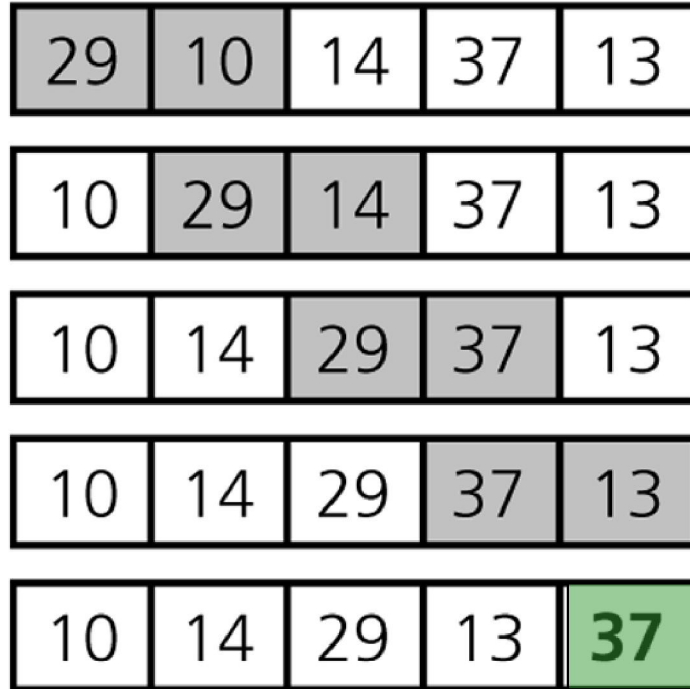
Bubble Sort: Idea

- Given an array of n items
 1. Compare pair of adjacent items
 2. Swap if the items are out of order
 3. Repeat until the end of array
 - The largest item will be at the last position
 4. Reduce n by 1 and go to Step 1

- Analogy
 - Large item is like “bubble” that floats to the end of the array

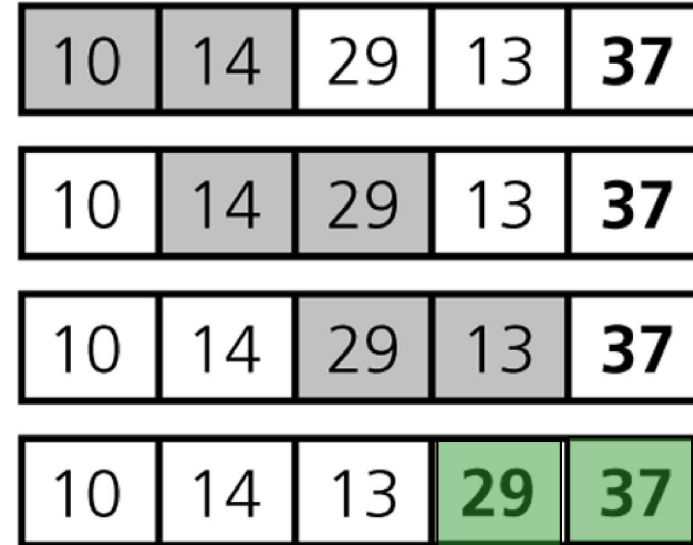
Bubble Sort: Illustration

(a) Pass 1



At the end of **Pass 1**, the largest item **37** is at the last position.

(b) Pass 2



At the end of **Pass 2**, the second largest item **29** is at the second last position.



Bubble Sort: Implementation

```
void bubbleSort(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        for (int j = 1; j <= i; j++) {  
            if (a[j-1] > a[j])  
                swap(a[j], a[j-1]);  
        }  
    }  
}
```

Step 1:
Compare
adjacent
pairs of
numbers

Step 2:
Swap if the
items are out
of order

29	10	14	37	13
----	----	----	----	----

<http://visualgo.net/sorting?create=29,10,14,37,13&mode=Bubble>

Bubble Sort: Analysis

- 1 iteration of the inner loop (test and swap) requires time bounded by a constant c
- Two nested loops
 - Outer loop: exactly n iterations
 - Inner loop:
 - when $i=0$, $(n-1)$ iterations
 - when $i=1$, $(n-2)$ iterations
 - ...
 - when $i=(n-1)$, 0 iterations
- Total number of iterations = $0+1+\dots+(n-1) = n(n-1)/2$
- Total time = $c n(n-1)/2 = \mathbf{O}(n^2)$

Bubble Sort: Early Termination

- Bubble Sort is inefficient with a $O(n^2)$ time complexity
- However, it has an interesting property
 - Given the following array, how many times will the inner loop swap a pair of item?

3	6	11	25	39
---	---	----	----	----

- Idea
 - If we go through the inner loop with no swapping
 - ➔ the array is sorted
 - ➔ can stop early!

Bubble Sort v2.0: Implementation

```
void bubbleSort2(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        bool is_sorted = true;  
        for (int j = 1; j <= i; j++) {  
            if (a[j-1] > a[j]) {  
                swap(a[j], a[j-1]);  
                is_sorted = false;  
            }  
        } // end of inner loop  
        if (is_sorted) return;  
    }  
}
```

Assume the array is sorted before the inner loop

Any swapping will invalidate the assumption

If the flag remains **true** after the inner loop → sorted!

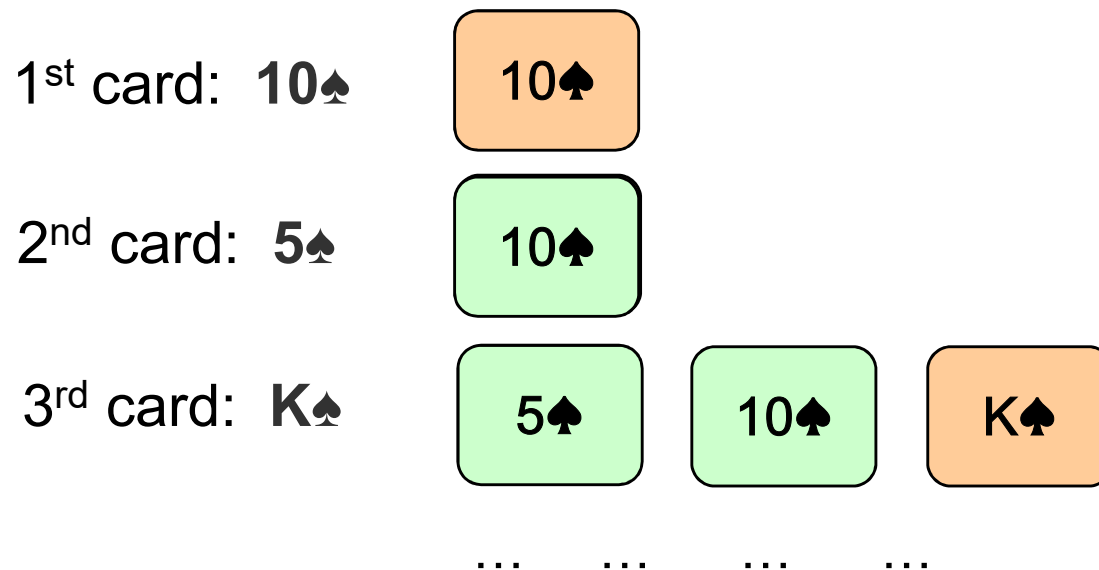
Bubble Sort v2.0: Analysis

- Worst-case
 - Input is in descending order
 - Running time remains the same: $O(n^2)$
- Best-case
 - Input is already in ascending order
 - The algorithm returns after a single outer iteration
 - Running time: $O(n)$

Insertion Sort

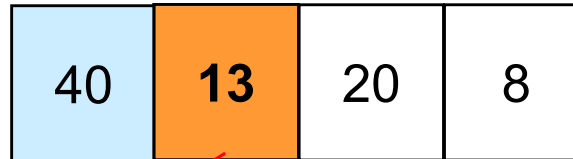
Insertion Sort: Idea

- Similar to how most people arrange a hand of poker cards
 - Start with one card in your hand
 - Pick the next card and insert it into its proper sorted order
 - Repeat previous step for all cards

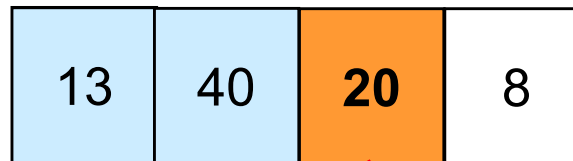


Insertion Sort: Illustration

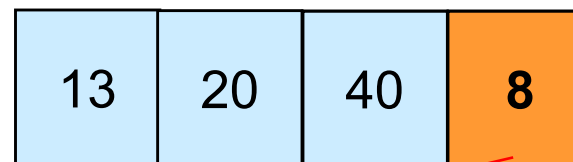
Start



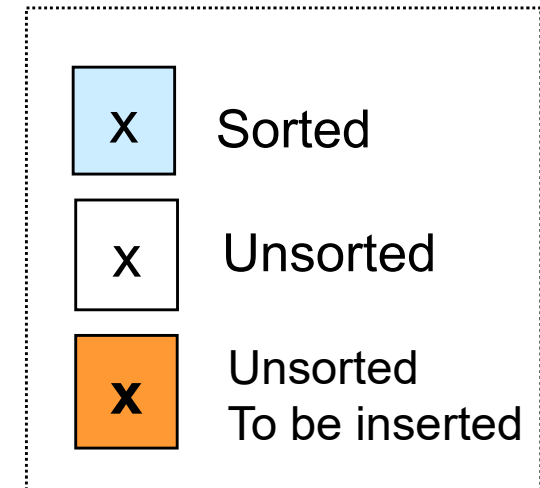
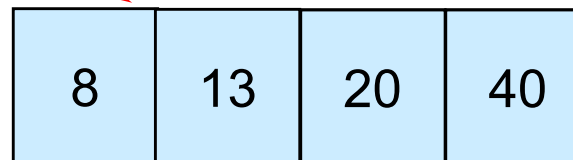
Iteration 1



Iteration 2



Iteration 3



<http://visualgo.net/sorting?create=40,13,20,8&mode=Insertion>

Insertion Sort: Implementation

```
void insertionSort(int a[], int n) {  
    for (int i = 1; i < n; i++) {  
        int next = a[i];  
        int j;  
  
        for (j = i-1; j >= 0 && a[j] > next; j--)  
            a[j+1] = a[j];  
  
        a[j+1] = next;  
    }  
}
```

next is the item to be inserted

Shift sorted items to make place for **next**

Insert **next** to the correct location

29	10	14	37	13
----	----	----	----	----

<http://visualgo.net/sorting?create=29,10,14,37,13&mode=Insertion>

Insertion Sort: Analysis

- Outer-loop executes $(n-1)$ times
- Number of times inner-loop is executed depends on the input
 - **Best-case:** the array is already sorted and $(a[j] > \text{next})$ is always false
 - No shifting of data is necessary
 - **Worst-case:** the array is reversely sorted and $(a[j] > \text{next})$ is always true
 - Insertion always occur at the front
- Therefore, the **best-case** time is $O(n)$
- And the **worst-case** time is $O(n^2)$

Merge Sort

Merge Sort: Idea

- Suppose we only know how to merge two sorted sets of elements into one
 - Merge $\{1, 5, 9\}$ with $\{2, 11\}$ \rightarrow $\{1, 2, 5, 9, 11\}$
- Question
 - Where do we get the two sorted sets in the first place?
- Idea (use **merge** to sort n items)
 - Merge each pair of elements into sets of 2
 - Merge each pair of sets of 2 into sets of 4
 - Repeat previous step for sets of 4 ...
 - Final step: merge 2 sets of $n/2$ elements to obtain a fully sorted set

Divide-and-Conquer Method

- A powerful problem solving technique
- Divide-and-conquer method solves problem in the following steps
 - **Divide step**
 - Divide the large problem into smaller problems
 - Recursively solve the smaller problems
 - **Conquer step**
 - Combine the results of the smaller problems to produce the result of the larger problem

Divide and Conquer: Merge Sort

- Merge Sort is a divide-and-conquer sorting algorithm
- Divide step
 - Divide the array into two (equal) halves
 - Recursively sort the two halves
- Conquer step
 - Merge the two halves to form a sorted array

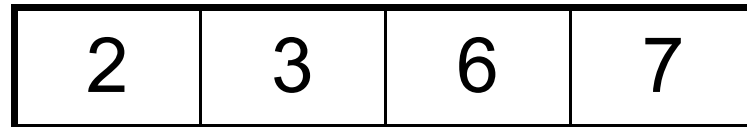
Merge Sort: Illustration



Divide into
two halves



Recursively
sort the
halves



Merge them



■ Question

- How should we sort the halves in the 2nd step?

Merge Sort: Implementation

```
void mergeSort(int a[], int low, int high) {  
    if (low < high) {  
        int mid = (low+high) / 2;  
  
        mergeSort(a, low, mid);  
        mergeSort(a, mid+1, high);  
  
        merge(a, low, mid, high);  
    }  
}
```

Merge sort on
a[low...high]

Divide a[] into two
halves and **recursively**
sort them

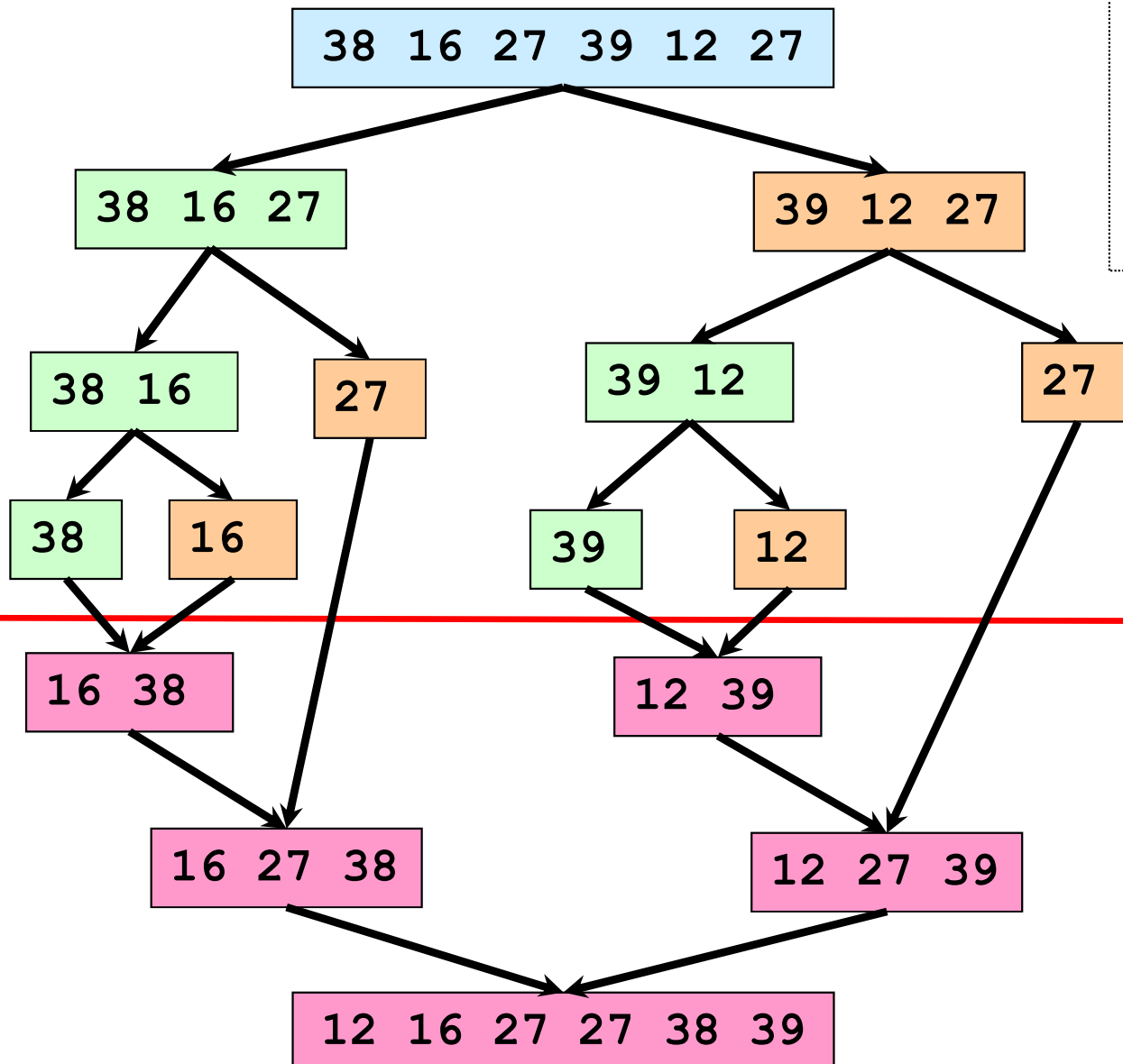
Conquer: merge the
two sorted halves

Function to merge
a[low...mid] and
a[mid+1...high] into
a[low...high]

■ Note

- **mergeSort()** is a recursive function
- **low >= high** is the base case, i.e. there is 0 or 1 item

Merge Sort: Example



```
mergeSort(a[low..mid])  
mergeSort(a[mid+1..high])  
merge(a[low..mid],  
      a[mid+1..high])
```

Divide Phase
Recursive call to
mergeSort()

Conquer Phase
Merge steps

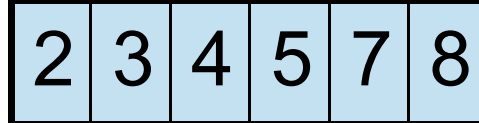
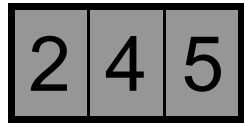
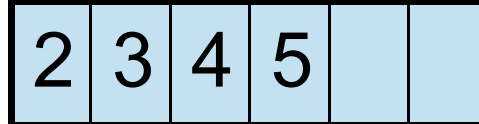
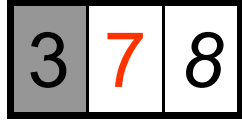
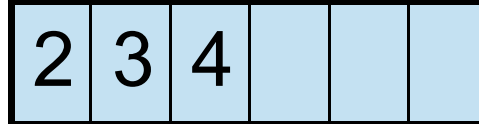
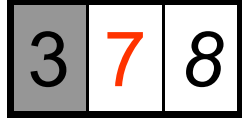
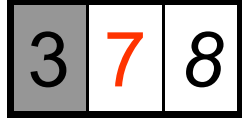
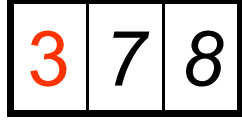
<http://visualgo.net/sorting?create=38,16,27,39,12,27&mode=Merge>

Merge Sort: Merge

a[0..2]

a[3..5]

b[0..5]



Two sorted halves to be merged

Merged result in a temporary array

x	Unmerged items
x	Items used for comparison
x	Merged items

Merge Sort: Merge Implementation

PS: C++ STL `<algorithm>` has [merge](#) subroutine too

```
void merge(int a[], int low, int mid, int high) {
```

```
    int n = high-low+1;
```

```
    int* b = new int[n];
```

```
    int left=low, right=mid+1, bIdx=0;
```

```
    while (left <= mid && right <= high) {
```

```
        if (a[left] <= a[right])
```

```
            b[bIdx++] = a[left++];
```

```
        else
```

```
            b[bIdx++] = a[right++];
```

```
    }
```

```
    // continue on next slide
```

b is a temporary array to store result

Normal Merging
Where both halves have unmerged items

Merge Sort: Merge Implementation

```
// continued from previous slide
```

```
while (left <= mid) b[bIdx++] = a[left++];  
while (right <= high) b[bIdx++] = a[right++];
```

```
for (int k = 0; k < n; k++)  
    a[low+k] = b[k];
```

Merged result
are copied
back into **a[]**

Remaining
items are
copied into
b[]

```
delete [] b;
```

Remember to free
allocated memory

■ Question

- Why do we need a temporary array **b[]**?

Merge Sort: Analysis

- In **mergeSort()**, the bulk of work is done in the **merge** step
- For **merge(a, low, mid, high)**
 - Let total items = $k = (\text{high} - \text{low} + 1)$
 - Number of comparisons $\leq k - 1$
 - Number of moves from original array to temporary array = k
 - Number of moves from temporary array back to original array = k
- In total, number of operations $\leq 3k - 1 = O(k)$
- The important question is
 - How many times is **merge()** called?

Merge Sort: Analysis

Level 0:
mergeSort n items

Level 1:
mergeSort $n/2$ items

Level 2:
mergeSort $n/2^2$ items

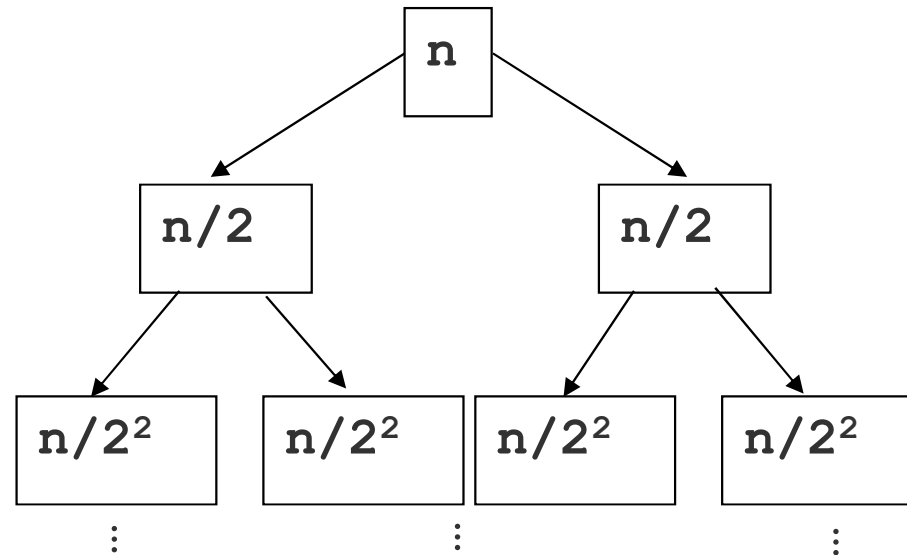
Level ($\lg n$):
mergeSort 1 item

Level 0:
1 call to mergeSort

Level 1:
2 calls to mergeSort

Level 2:
 2^2 calls to mergeSort

Level ($\lg n$):
 $2^{\lg n} (= n)$ calls to mergeSort



$$n/(2^k) = 1 \rightarrow n = 2^k \rightarrow k = \lg n$$

Merge Sort: Analysis

- **Level 0:** **0** call to `merge()`
- **Level 1:** **1** calls to `merge()` with $n/2$ items in each half,
 $O(1 \times 2 \times n/2) = O(n)$ time
- **Level 2:** **2** calls to `merge()` with $n/2^2$ items in each half,
 $O(2 \times 2 \times n/2^2) = O(n)$ time
- **Level 3:** **2^2** calls to `merge()` with $n/2^3$ items in each half,
 $O(2^2 \times 2 \times n/2^3) = O(n)$ time
- ...
- **Level ($\lg n$):** $2^{\lg(n) - 1} (= n/2)$ calls to `merge()` with $n/2^{\lg(n)} (= 1)$ item in each half, $O(n)$ time
- Total time complexity = $O(n \lg(n))$
- **Optimal** comparison-based sorting method

Merge Sort: Pros and Cons

■ Pros

- The performance is guaranteed, i.e. unaffected by original ordering of the input
- Suitable for extremely large number of inputs
 - Can operate on the input portion by portion

■ Cons

- Not easy to implement
- Requires additional storage during merging operation
 - $O(n)$ extra memory storage needed

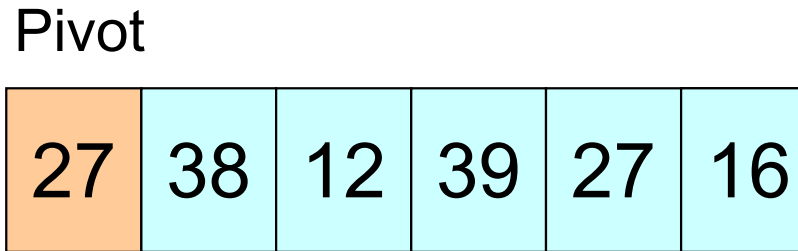
Quick Sort

Quick Sort: Idea

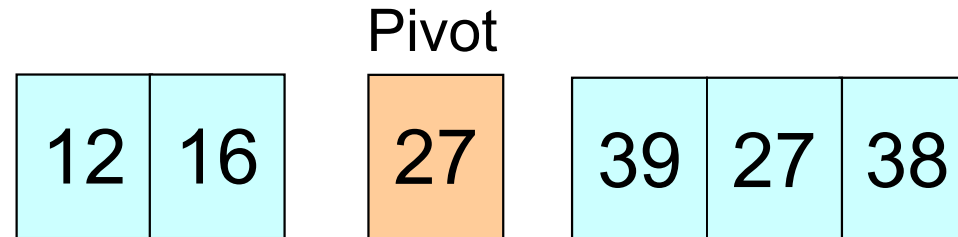
- **Quick Sort** is a divide-and-conquer algorithm
 - **Divide step**
 - Choose an item p (known as **pivot**) and partition the items of $a[i..j]$ into two parts
 - Items that are smaller than p
 - Items that are greater than or equal to p
 - Recursively sort the two parts
 - **Conquer step**
 - Do nothing!
- In comparison, **Merge Sort** spends most of the time in conquer step but very little time in divide step

Quick Sort: Divide Step Example

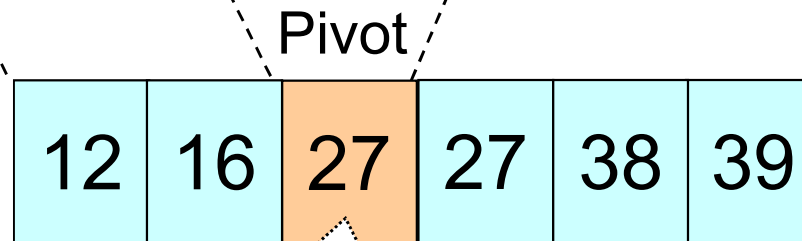
Choose first element as pivot



Partition $a[]$ about the pivot 27



Recursively sort the two parts



Notice anything special about the position of pivot in the final sorted items?

Quick Sort: Implementation

```
void quickSort(int a[], int low, int high) {  
    if (low < high) {  
        int pivotIdx = partition(a, low, high)  
  
        quickSort(a, low, pivotIdx-1);  
        quickSort(a, pivotIdx+1, high);  
    }  
}
```

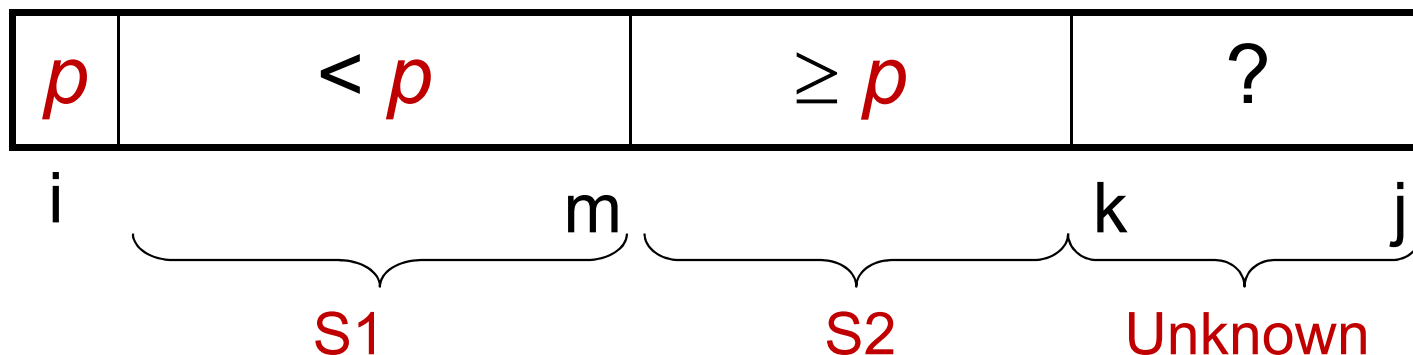
Partition
a[low...high]
and return the
index of the
pivot item

Recursively sort
the two portions

- **partition()** splits **a[low...high]** into two portions
 - **a[low ... pivot-1]** and **a[pivot+1 ... high]**
- Pivot item does not participate in any further sorting

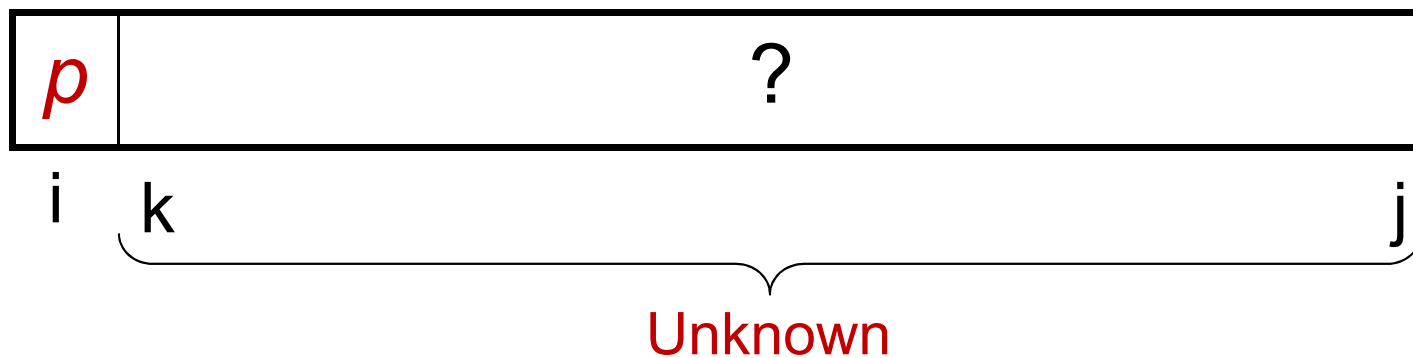
Quick Sort: Partition Algorithm

- To partition $a[i...j]$, we choose $a[i]$ as the pivot p
 - Why choose $a[i]$? Are there other choices?
- The remaining items (i.e. $a[i+1...j]$) are divided into 3 regions
 - **S1** = $a[i+1...m]$ where items $< p$
 - **S2** = $a[m+1...k-1]$ where item $\geq p$
 - **Unknown** (unprocessed) = $a[k...j]$, where items are yet to be assigned to S1 or S2



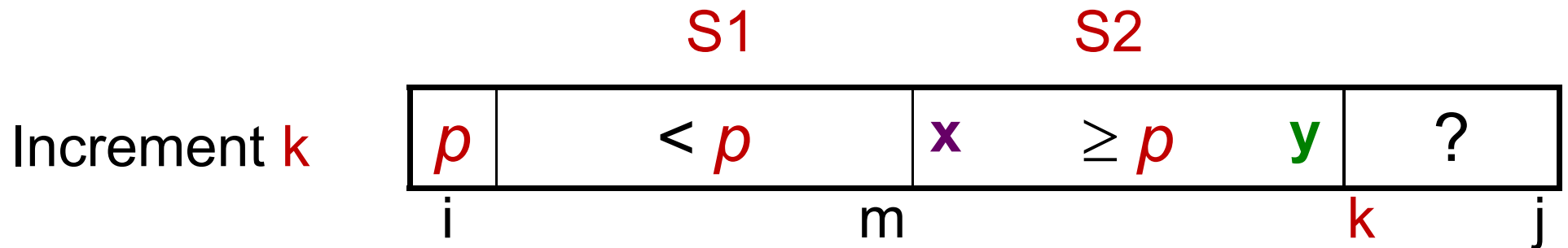
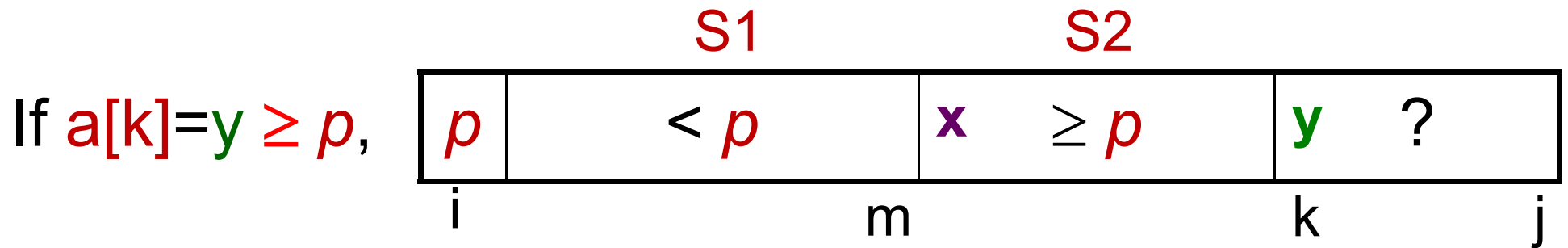
Quick Sort: Partition Algorithm

- Initially, regions **S1** and **S2** are empty
 - All items excluding p are in the **unknown** region
- For each item $a[k]$ in the **unknown** region
 - Compare $a[k]$ with p
 - If $a[k] \geq p$, put it into **S2**
 - Otherwise, put $a[k]$ into **S1**



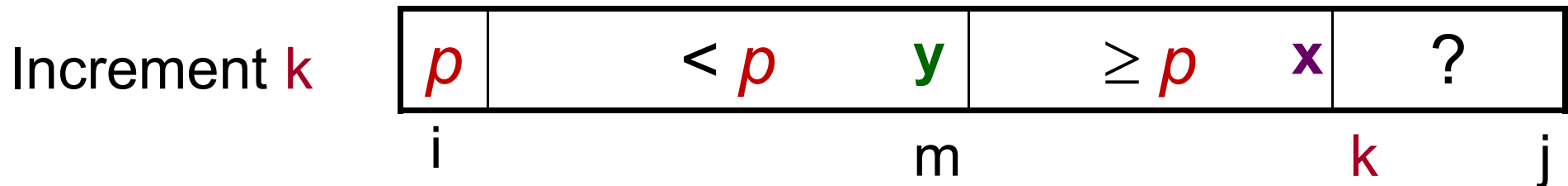
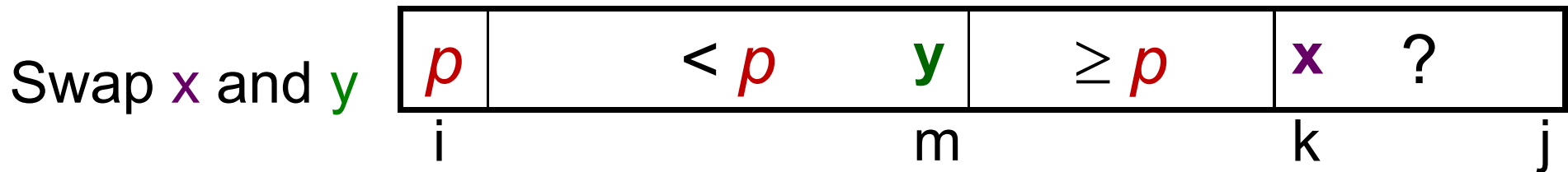
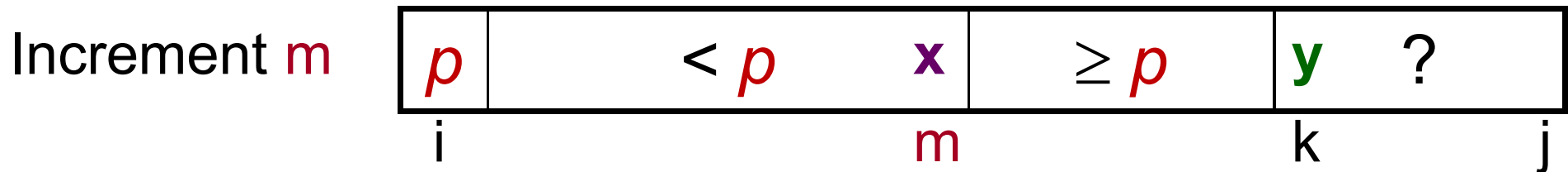
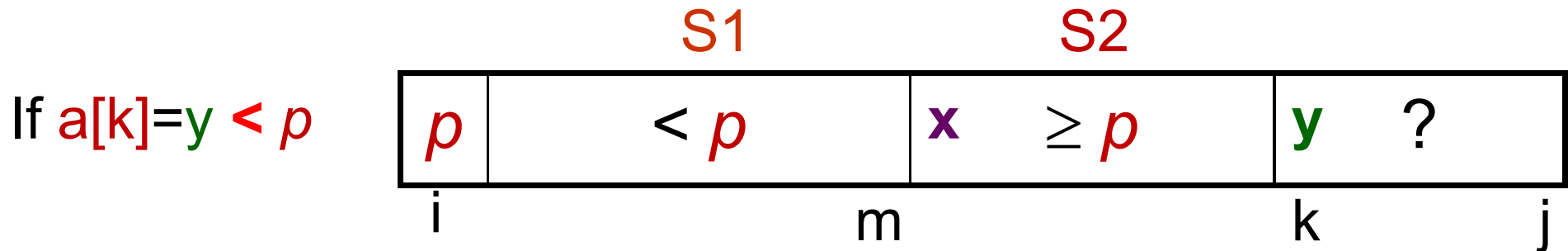
Quick Sort: Partition Algorithm

- Case 1: if $a[k] \geq p$



Quick Sort: Partition Algorithm

- Case 2: if $a[k] < p$



Quick Sort: Partition Implementation

PS: C++ STL `<algorithm>` has [partition](#) subroutine too

```
int partition(int a[], int i, int j) {
```

```
    int p = a[i];
```

```
    int m = i;
```

```
    for (int k = i+1; k <= j; k++) {
```

```
        if (a[k] < p) {
```

```
            m++;
```

```
            swap(a[k], a[m]);
```

```
        }
```

```
        else {
```

```
        }
```

```
    }
```

```
    swap(a[i], a[m]);
```

```
    return m;
```

```
}
```

p is the pivot

S1 and **S2** empty initially

Go through each element in unknown region

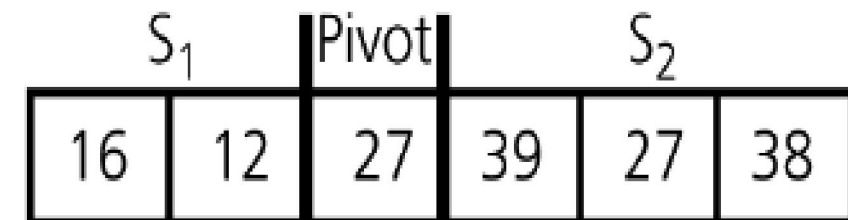
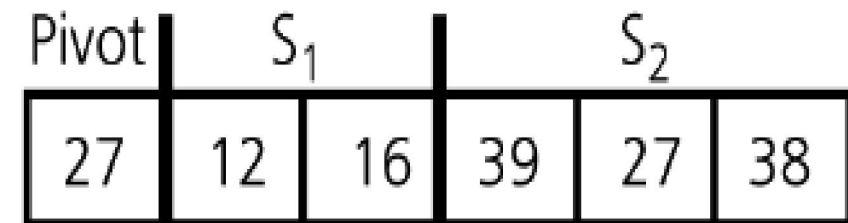
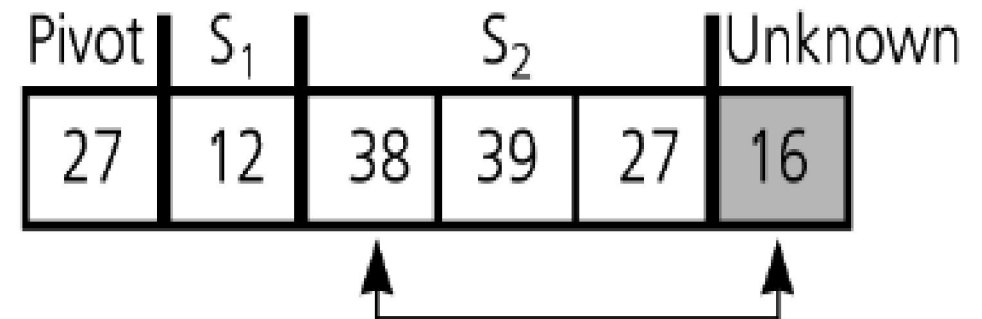
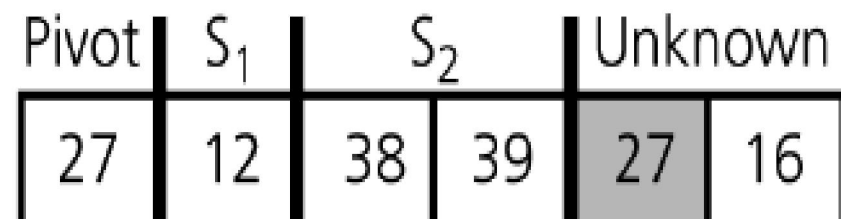
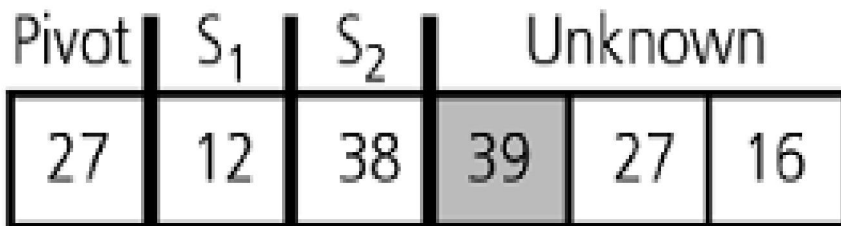
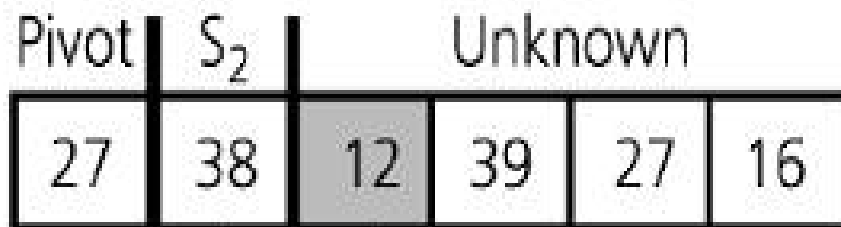
Case 2

Case 1: Do nothing!

Swap pivot with **a[m]**

m is the index of pivot

Quick Sort: Partition Example



<http://visualgo.net/sorting?create=27,38,12,39,27,16&mode=Quick>

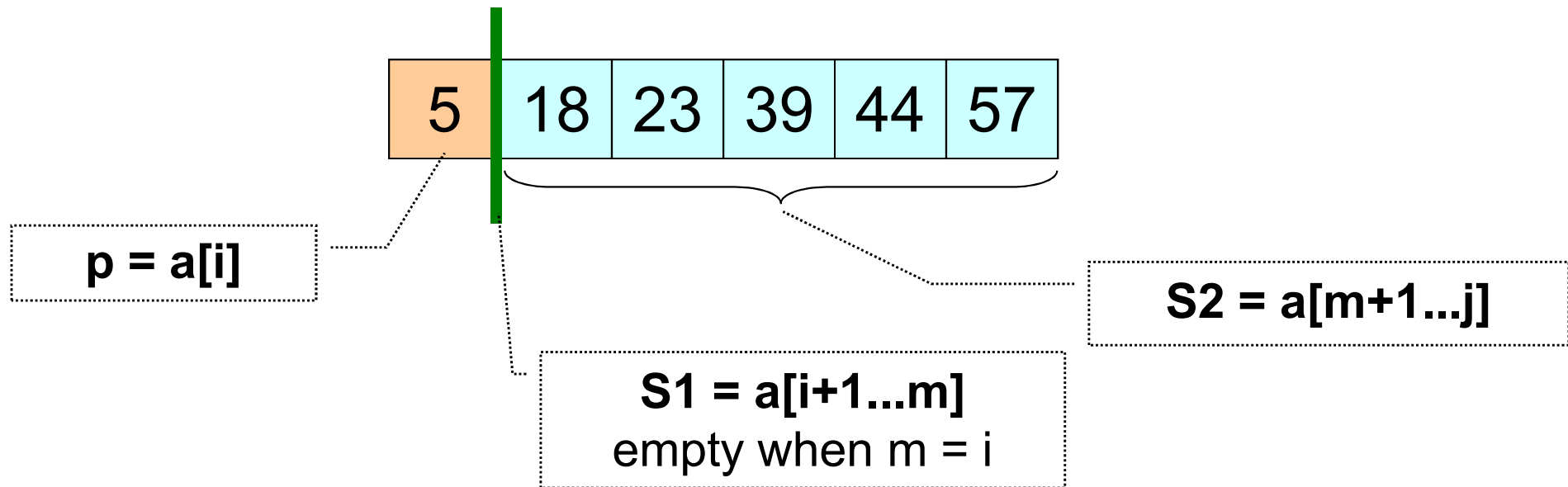
Quick Sort: Partition Analysis

- There is only a single for-loop
 - Number of iterations = number of items, n , in the unknown region
 - $n = \text{high} - \text{low}$
 - Complexity is $O(n)$

- Similar to **Merge Sort**, the complexity is then dependent on the number of times **partition()** is called

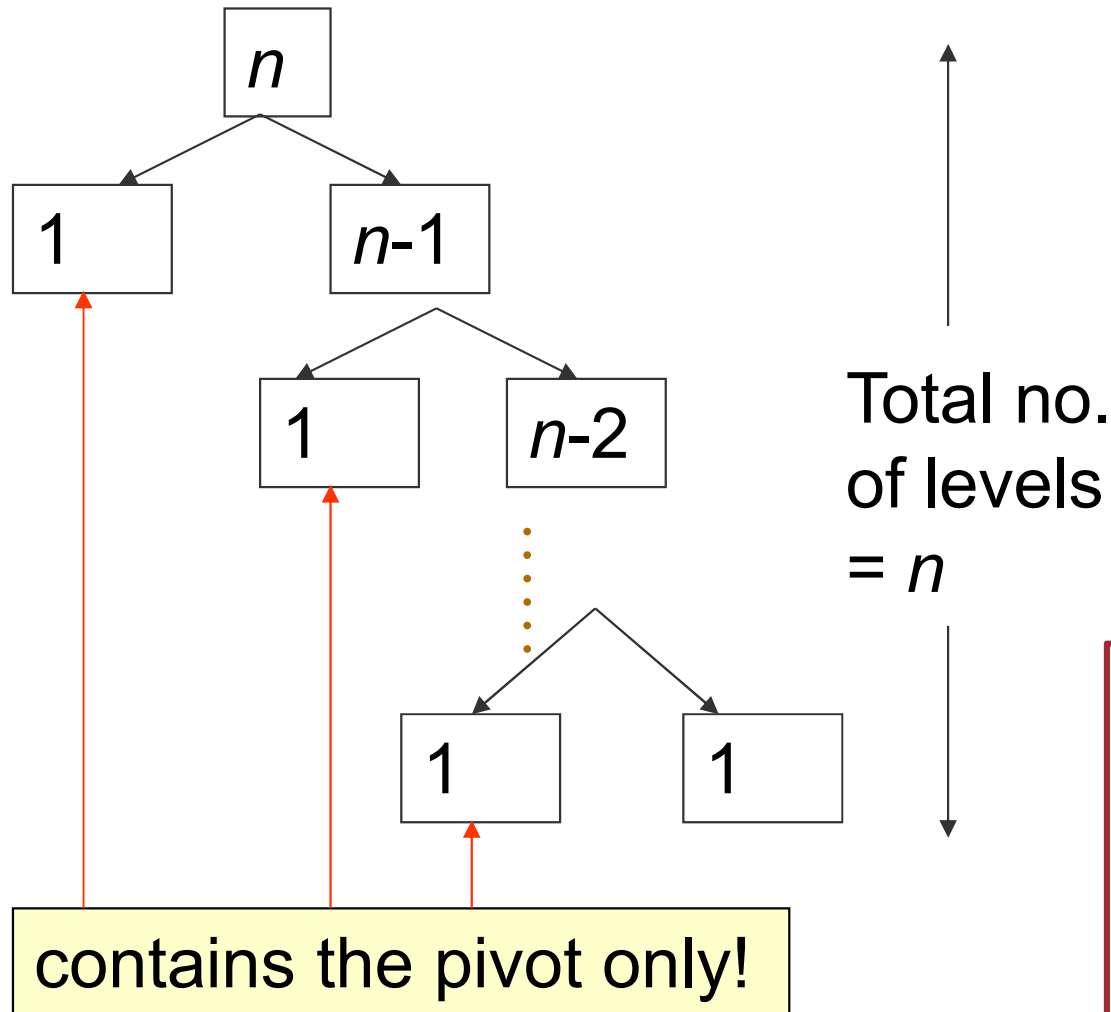
Quick Sort: Worst Case Analysis

- When the array is already in ascending order



- What is the pivot index returned by **partition()**?
 - What is the effect of **swap(a, i, m)**?
- **S1** is empty, while **S2** contains every item except the pivot

Quick Sort: Worst Case Analysis



As each partition takes linear time, the algorithm in its worst case has n levels and hence it takes time $n+(n-1)+\dots+1 = O(n^2)$

Quick Sort: Best/Average Case Analysis

- Best case occurs when partition always splits the array into **two equal halves**
 - Depth of recursion is $\log n$
 - Each level takes n or fewer comparisons, so the time complexity is $O(n \log n)$
- In practice, worst case is rare, and on the average we get some good splits and some bad ones (details in CS3230 :O)
 - Average time is also $O(n \log n)$

Lower Bound: Comparison-Based Sort

- It is known that
 - All **comparison-based** sorting algorithms have a complexity **lower bound** of $n \log n$
- Therefore, any comparison-based sorting algorithm with **worst-case complexity** $O(n \log n)$ is **optimal**